

**THIS PAPER MUST NOT BE REMOVED
FROM THE EXAMINATION ROOM**

**STUDENT NAME:
STUDENT NUMBER:**

Internal Students Only

THE UNIVERSITY OF QUEENSLAND

**School of Information Technology
& Electrical Engineering**

Final Exam – 2012

ELEC 3004 / 7312:

Signals Systems & Controls

(Formula Sheet)

CLOSED BOOK

TIME: One Hundred and Seventy Five (175) minutes for working

Five (5) minutes for perusal before examination begins

ANSWER ALL QUESTIONS ON SHEET PROVIDED

QUESTIONS CARRY THE NUMBER OF MARKS INDICATED

Drawing instruments and one battery-operated or solar-powered electronic calculator may be used but NO pre-programmed material or calculator instruction booklets are allowed in the examination room.

Table 1: Commonly used Formulae

The Laplace Transform

$$F(s) = \int_0^{\infty} f(t)e^{-st} dt$$

The \mathcal{Z} Transform

$$F(z) = \sum_{n=0}^{\infty} f[n]z^{-n}$$

IIR Filter Pre-warp

$$\omega_a = \frac{2}{\Delta t} \tan\left(\frac{\omega_d \Delta t}{2}\right)$$

Bi-linear Transform

$$s = \frac{2(1 - z^{-1})}{\Delta t(1 + z^{-1})}$$

FIR Filter Coefficients

$$c_n = \frac{\Delta t}{\pi} \int_0^{\pi/\Delta t} H_d(\omega) \cos(n\omega\Delta t) d\omega$$

Table 2: Comparison of Fourier representations.

| Time Domain | Periodic | Non-periodic | |
|--------------------|--|---|---------------------|
| | Discrete Fourier Transform | Discrete-Time Fourier Transform | |
| Discrete | $\tilde{X}[k] = \frac{1}{N} \sum_{n=0}^{N-1} \tilde{x}[n]e^{-j2\pi kn/N}$ $\tilde{x}[n] = \sum_{k=0}^{N-1} \tilde{X}[k]e^{j2\pi kn/N}$ | $X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x[n]e^{-j\omega n}$ $x[n] = \frac{1}{2\pi} \int_{-\pi}^{\pi} X(e^{j\omega})e^{j\omega n} d\omega$ | Periodic |
| | Complex Fourier Series | Fourier Transform | |
| Continuous | $X[k] = \frac{1}{T} \int_{-T/2}^{T/2} \tilde{x}(t)e^{-j2\pi kt/T} dt$ $\tilde{x}(t) = \sum_{k=-\infty}^{\infty} X[k]e^{j2\pi kt/T}$ | $X(j\omega) = \int_{-\infty}^{\infty} x(t)e^{-j\omega t} dt$ $x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\omega)e^{j\omega t} d\omega$ | Non-periodic |
| | Discrete | Continuous | Freq. Domain |

ELEC 3004 / 7312: Signals Systems & Controls
Final Exam – 2012

Table 3: Selected Fourier, Laplace and z -transform pairs.

| Signal | \longleftrightarrow | Transform | ROC |
|--|---------------------------------|---|-------------------------|
| $\tilde{x}[n] = \sum_{p=-\infty}^{\infty} \delta[n - pN]$ | \xleftrightarrow{DFT} | $\tilde{X}[k] = \frac{1}{N}$ | |
| $x[n] = \delta[n]$ | \xleftrightarrow{DTFT} | $X(e^{j\omega}) = 1$ | |
| $\tilde{x}(t) = \sum_{p=-\infty}^{\infty} \delta(t - pT)$ | \xleftrightarrow{FS} | $X[k] = \frac{1}{T}$ | |
| $\delta_T[t] = \sum_{p=-\infty}^{\infty} \delta(t - pT)$ | \xleftrightarrow{FT} | $X(j\omega) = \frac{2\pi}{T} \sum_{k=-\infty}^{\infty} \delta(\omega - k\omega_0)$ | |
| $\cos(\omega_0 t)$ | \xleftrightarrow{FT} | $X(j\omega) = \pi\delta(\omega - \omega_0) + \pi\delta(\omega + \omega_0)$ | |
| $\sin(\omega_0 t)$ | \xleftrightarrow{FT} | $X(j\omega) = j\pi\delta(\omega + \omega_0) - j\pi\delta(\omega - \omega_0)$ | |
| $x(t) = \begin{cases} 1 & \text{when } t \leq T_0, \\ 0 & \text{otherwise.} \end{cases}$ | \xleftrightarrow{FT} | $X(j\omega) = \frac{2\sin(\omega T_0)}{\omega}$ | |
| $x(t) = \frac{1}{\pi t} \sin(\omega_c t)$ | \xleftrightarrow{FT} | $X(j\omega) = \begin{cases} 1 & \text{when } \omega \leq \omega_c , \\ 0 & \text{otherwise.} \end{cases}$ | |
| $x(t) = \delta(t)$ | \xleftrightarrow{FT} | $X(j\omega) = 1$ | |
| $x(t) = \delta(t - t_0)$ | \xleftrightarrow{FT} | $X(j\omega) = e^{-j\omega t_0}$ | |
| $x(t) = u(t)$ | \xleftrightarrow{FT} | $X(j\omega) = \pi\delta(\omega) + \frac{1}{j\omega}$ | |
| $x[n] = \frac{\omega_c}{\pi} \text{sinc } \omega_c n$ | \xleftrightarrow{DTFT} | $X(e^{j\omega}) = \begin{cases} 1 & \text{when } \omega < \omega_c , \\ 0 & \text{otherwise.} \end{cases}$ | |
| $x(t) = \delta(t)$ | $\xleftrightarrow{\mathcal{L}}$ | $X(s) = 1$ | all s |
| (unit step) $x(t) = u(t)$ | $\xleftrightarrow{\mathcal{L}}$ | $X(s) = \frac{1}{s}$ | |
| (unit ramp) $x(t) = t$ | $\xleftrightarrow{\mathcal{L}}$ | $X(s) = \frac{1}{s^2}$ | |
| $x(t) = \sin(s_0 t)$ | $\xleftrightarrow{\mathcal{L}}$ | $X(s) = \frac{s_0}{(s^2 + s_0^2)}$ | |
| $x(t) = \cos(s_0 t)$ | $\xleftrightarrow{\mathcal{L}}$ | $X(s) = \frac{s}{(s^2 + s_0^2)}$ | |
| $x(t) = e^{s_0 t} u(t)$ | $\xleftrightarrow{\mathcal{L}}$ | $X(s) = \frac{1}{s - s_0}$ | $\Re\{s\} > \Re\{s_0\}$ |
| $x[n] = \delta[n]$ | $\xleftrightarrow{\mathcal{Z}}$ | $X(z) = 1$ | all z |
| $x[n] = \delta[n - m]$ | $\xleftrightarrow{\mathcal{Z}}$ | $X(z) = z^{-m}$ | |
| $x[n] = u[n]$ | $\xleftrightarrow{\mathcal{Z}}$ | $X(z) = \frac{z}{z - 1}$ | |
| $x[n] = z_0^n u[n]$ | $\xleftrightarrow{\mathcal{Z}}$ | $X(z) = \frac{1}{1 - z_0 z^{-1}}$ | $ z > z_0 $ |
| $x[n] = -z_0^n u[-n - 1]$ | $\xleftrightarrow{\mathcal{Z}}$ | $X(z) = \frac{1}{1 - z_0 z^{-1}}$ | $ z < z_0 $ |
| $x[n] = a^n u[n]$ | $\xleftrightarrow{\mathcal{Z}}$ | $X(z) = \frac{z}{z - a}$ | $ z < a $ |

ELEC 3004 / 7312: Signals Systems & Controls
Final Exam – 2012

Table 4: Properties of the Discrete-time Fourier Transform.

| Property | Time domain | Frequency domain |
|-----------------------------|--|--|
| Linearity | $ax_1[n] + bx_2[n]$ | $aX_1(e^{j\omega}) + bX_2(e^{j\omega})$ |
| Differentiation (frequency) | $nx[n]$ | $j \frac{dX(e^{j\omega})}{d\omega}$ |
| Time-shift | $x[n - n_0]$ | $e^{-j\omega n_0} X(e^{j\omega})$ |
| Frequency-shift | $e^{j\omega_0 n} x[n]$ | $X(e^{j(\omega - \omega_0)})$ |
| Convolution | $x_1[n] * x_2[n]$ | $X_1(e^{j\omega}) X_2(e^{j\omega})$ |
| Modulation | $x_1[n] x_2[n]$ | $\frac{1}{2\pi} X_1(e^{j\omega}) \otimes X_2(e^{j\omega})$ |
| Time-reversal | $x[-n]$ | $X(e^{-j\omega})$ |
| Conjugation | $x^*[n]$ | $X^*(e^{-j\omega})$ |
| Symmetry (real) | $\Im\{x[n]\} = 0$ | $X(e^{j\omega}) = X^*(e^{-j\omega})$ |
| Symmetry (imag) | $\Re\{x[n]\} = 0$ | $X(e^{j\omega}) = -X^*(e^{-j\omega})$ |
| Parseval | $\sum_{n=-\infty}^{\infty} x[n] ^2 = \frac{1}{2\pi} \int_{-\pi}^{\pi} X(e^{j\omega}) ^2 d\omega$ | |

Table 5: Properties of the Fourier series.

| Property | Time domain | Frequency domain |
|------------------------|--|-----------------------------|
| Linearity | $a\tilde{x}_1(t) + b\tilde{x}_2(t)$ | $aX_1[k] + bX_2[k]$ |
| Differentiation (time) | $\frac{d\tilde{x}(t)}{dt}$ | $\frac{j2\pi k}{T} X[k]$ |
| Time-shift | $\tilde{x}(t - t_0)$ | $e^{-j2\pi k t_0 / T} X[k]$ |
| Frequency-shift | $e^{j2\pi k_0 t / T} \tilde{x}(t)$ | $X[k - k_0]$ |
| Convolution | $\tilde{x}_1(t) \otimes \tilde{x}_2(t)$ | $T X_1[k] X_2[k]$ |
| Modulation | $\tilde{x}_1(t) \tilde{x}_2(t)$ | $X_1[k] * X_2[k]$ |
| Time-reversal | $\tilde{x}(-t)$ | $X[-k]$ |
| Conjugation | $\tilde{x}^*(t)$ | $X^*[-k]$ |
| Symmetry (real) | $\Im\{\tilde{x}(t)\} = 0$ | $X[k] = X^*[-k]$ |
| Symmetry (imag) | $\Re\{\tilde{x}(t)\} = 0$ | $X[k] = -X^*[-k]$ |
| Parseval | $\frac{1}{T} \int_{-T/2}^{T/2} \tilde{x}(t) ^2 dt = \sum_{k=-\infty}^{\infty} X[k] ^2$ | |

ELEC 3004 / 7312: Signals Systems & Controls
Final Exam – 2012

Table 6: Properties of the Fourier transform.

| Property | Time domain | Frequency domain |
|-----------------|---|--|
| Linearity | $a\tilde{x}_1(t) + b\tilde{x}_2(t)$ | $aX_1(j\omega) + bX_2(j\omega)$ |
| Duality | $X(jt)$ | $2\pi x(-\omega)$ |
| Differentiation | $\frac{dx(t)}{dt}$ | $j\omega X(j\omega)$ |
| Integration | $\int_{-\infty}^t x(\tau) d\tau$ | $\frac{1}{j\omega} X(j\omega) + \pi X(j0)\delta(\omega)$ |
| Time-shift | $x(t - t_0)$ | $e^{-j\omega t_0} X(j\omega)$ |
| Frequency-shift | $e^{j\omega_0 t} x(t)$ | $X(j(\omega - \omega_0))$ |
| Convolution | $x_1(t) * x_2(t)$ | $X_1(j\omega)X_2(j\omega)$ |
| Modulation | $x_1(t)x_2(t)$ | $\frac{1}{2\pi} X_1(j\omega) * X_2(j\omega)$ |
| Time-reversal | $x(-t)$ | $X(-j\omega)$ |
| Conjugation | $x^*(t)$ | $X^*(-j\omega)$ |
| Symmetry (real) | $\Im\{x(t)\} = 0$ | $X(j\omega) = X^*(-j\omega)$ |
| Symmetry (imag) | $\Re\{x(t)\} = 0$ | $X(j\omega) = -X^*(-j\omega)$ |
| Scaling | $x(at)$ | $\frac{1}{ a } X\left(\frac{j\omega}{a}\right)$ |
| Parseval | $\int_{-\infty}^{\infty} x(t) ^2 dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\omega) ^2 d\omega$ | |

Table 7: Properties of the z -transform.

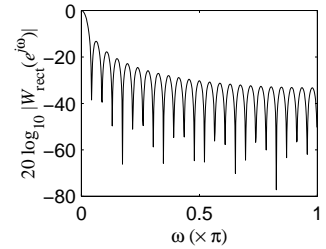
| Property | Time domain | z -domain | ROC |
|------------------------|---|-----------------------|----------------------------------|
| Linearity | $ax_1[n] + bx_2[n]$ | $aX_1(z) + bX_2(z)$ | $\subseteq R_{x_1} \cap R_{x_2}$ |
| Time-shift | $x[n - n_0]$ | $z^{-n_0} X(z)$ | R_x^\dagger |
| Scaling in z | $z_0^n x[n]$ | $X(z/z_0)$ | $ z_0 R_x$ |
| Differentiation in z | $nx[n]$ | $-z \frac{dX(z)}{dz}$ | R_x^\dagger |
| Time-reversal | $x[-n]$ | $X(1/z)$ | $1/R_x$ |
| Conjugation | $x^*[n]$ | $X^*(z^*)$ | R_x |
| Symmetry (real) | $\Im\{x[n]\} = 0$ | $X(z) = X^*(z^*)$ | |
| Symmetry (imag) | $\Re\{X[n]\} = 0$ | $X(z) = -X^*(z^*)$ | |
| Convolution | $x_1[n] * x_2[n]$ | $X_1(z)X_2(z)$ | $\subseteq R_{x_1} \cap R_{x_2}$ |
| Initial value | $x[n] = 0, n < 0 \Rightarrow x[0] = \lim_{z \rightarrow \infty} X(z)$ | | |

[†] $z = 0$ or $z = \infty$ may have been added or removed from the ROC.

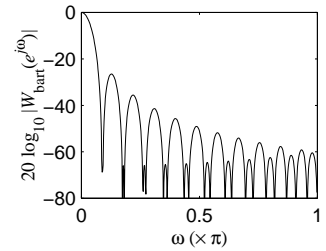
Table 8: Commonly used window functions.

Rectangular:

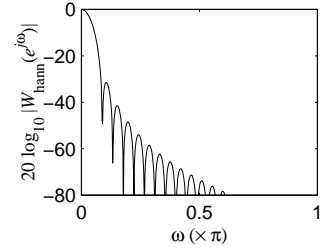
$$w_{\text{rect}}[n] = \begin{cases} 1 & \text{when } 0 \leq n \leq M, \\ 0 & \text{otherwise.} \end{cases}$$

*Bartlett (triangular):*

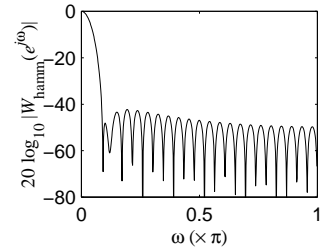
$$w_{\text{bart}}[n] = \begin{cases} 2n/M & \text{when } 0 \leq n \leq M/2, \\ 2 - 2n/M & \text{when } M/2 \leq n \leq M, \\ 0 & \text{otherwise.} \end{cases}$$

*Hanning:*

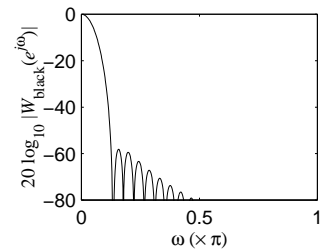
$$w_{\text{hann}}[n] = \begin{cases} \frac{1}{2} - \frac{1}{2} \cos(2\pi n/M) & \text{when } 0 \leq n \leq M, \\ 0 & \text{otherwise.} \end{cases}$$

*Hamming:*

$$w_{\text{hamm}}[n] = \begin{cases} 0.54 - 0.46 \cos(2\pi n/M) & \text{when } 0 \leq n \leq M, \\ 0 & \text{otherwise.} \end{cases}$$

*Blackman:*

$$w_{\text{black}}[n] = \begin{cases} 0.42 - 0.5 \cos(2\pi n/M) \\ \quad + 0.08 \cos(4\pi n/M) & \text{when } 0 \leq n \leq M, \\ 0 & \text{otherwise.} \end{cases}$$



| Type of Window | Peak Side-Lobe Amplitude (Relative; dB) | Approximate Width of Main Lobe | Peak Approximation Error, $20 \log_{10} \delta$ (dB) |
|----------------|--|-----------------------------------|---|
| Rectangular | -13 | $4\pi/(M+1)$ | -21 |
| Bartlett | -25 | $8\pi/M$ | -25 |
| Hanning | -31 | $8\pi/M$ | -44 |
| Hamming | -41 | $8\pi/M$ | -53 |
| Blackman | -57 | $12\pi/M$ | -74 |