



LTI & Laplace Transforms

ELEC 3004: Signals, Systems & Control

Dr. Surya Singh, Prof. Brian Lovell & Dr. Paul Pounds

Lecture # 4

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elec3004@itee.uq.edu.au

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Schedule of Events

Week	Date	Lecture Title
1	1-Mar	Overview
2	5-Mar	Signals & Systems
	8-Mar	Sampling
3	12-Mar	LTI & Laplace Transforms
	15-Mar	Convolution
4	19-Mar	Discrete Fourier Series
	22-Mar	Fourier Transform
5	26-Mar	Fourier Transform Operations
	29-Mar	Applications: DFFT and DCT
6	2-Apr	Exam 1 (10%)
	5-Apr	(Guest Lecture from Industry)
7	16-Apr	Data Acquisition & Interpolation
	19-Apr	Noise
8	23-Apr	Filters & IIR Filters
	26-Apr	FIR Filters
9	30-Apr	Multirate Filters
	3-May	Filter Selection
10	7-May	Holiday
	10-May	Quiz (10%)
11	14-May	z-T Transform
	17-May	Introduction to Digital Control
12	21-May	Stability of Digital Systems
	24-May	Estimation
13	28-May	Kalman Filters & GPS
	31-May	Applications in Industry



Overview

- Laplace transform
 - Finite power signals
 1. Unilateral Laplace transform
 2. Bilateral Laplace transform
- Transform Analysis of Linear systems
 - Circuit Analysis
 - Transfer functions

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Laplace Transform

- Problem: FT of a signal may not always exist!
 - finite power (and not periodic),
 - e.g., $x(t) = u(t)\exp(-at)$ with $a < 0$
 - Or $x(t) = u(t)\cos(5t)$!
- Solution: Force signal to have finite energy
 - Multiply by convergence factor $\exp(-\sigma t)$
 - i.e., new signal $x_\sigma(t) = \exp(-\sigma t)x(t)$
 - Therefore, FT of $x_\sigma(t)$ exists

$$\begin{array}{l} X_\sigma(w) = \int_{-\infty}^{\infty} x_\sigma(t) \exp(-j\omega t) dt \\ \text{Rearranging...} \\ X_\sigma(w) = \int_{-\infty}^{\infty} x(t) \exp(-(\sigma + j\omega)t) dt \end{array} \quad \begin{array}{l} \text{Fourier} \\ \Downarrow \\ \text{Laplace} \end{array}$$

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Bilateral Laplace Transform

- For compactness we write

$$- s = \sigma + j\omega$$

Note:

$$X(s) = \int_{-\infty}^{\infty} x(t) \exp(-st) dt$$

Laplace transform
 $X(s) = \mathcal{L}\{x(t)\}$

$$x(t) = \frac{1}{2\pi j} \int_{\sigma - j\infty}^{\sigma + j\infty} X(s) \exp(st) ds$$

Inverse Laplace transform
 $x(t) = \mathcal{L}^{-1}\{X(s)\}$

$$x(t) = \exp(\sigma t) x_{\sigma}(t) \quad \text{i.e., } \times \text{ by inverse of converge factor}$$

$$= \exp(\sigma t) \frac{1}{2\pi} \int_{-\infty}^{\infty} X_{\sigma}(\omega) \exp(j\omega t) d\omega \quad \text{i.e., } \mathcal{F}^{-1}\{X_{\sigma}(\omega)\}$$

$$= \frac{1}{2\pi} \int_{-\infty}^{\infty} X_{\sigma}(\omega) \exp((\sigma + j\omega)t) d\omega \quad \text{Finally re-arrange}$$

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Unilateral Laplace Transform

- Problem with *two-sided* (bilateral) transform
 - choice of σ can cause ambiguities in $\mathcal{L}^{-1}\{X(s)\}$
 - i.e., as different $x(t)$'s have same $X(s)$!
 - e.g., $\mathcal{L}\{\exp(at)u(t)\} = \mathcal{L}\{-\exp(at)u(-t)\}$
- Solution: assume $x(t)$ to be causal (*one-sided*)
 - i.e., $x(t) = 0$ when $t < 0$
 - This is termed the *unilateral* Laplace Transform
 - Integration is now from $0 \leq t < \infty$
- This solution works for *most* practical signals
 - Bilateral required for (non-deterministic) random signals
 - (see later)

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Unilateral Laplace Transform

- One-sided Laplace transform

$$X(s) = \int_{0^-}^{\infty} x(t) \exp(-st) dt$$

0⁻ indicates origin is included in integration $0 \leq t < \infty$

- Laplace transform
 - $X(s) = L\{x(t)\}$
- Inverse Laplace transform
 - $x(t) = L^{-1}\{X(s)\}$

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- Consider signal

Convergence of Laplace Transform

$$x(t) = \exp(-at)u(t)$$

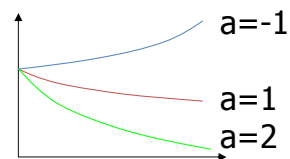
$$X(s) = \int_0^{\infty} \exp(-(s+a)t) dt$$

$$= \int_0^{\infty} \exp(-(\sigma+a)t) \exp(-j\omega t) dt$$

$$= \frac{-1}{s+a} [\exp(-(s+a)t)]_0^{\infty}$$

$$= \frac{1}{(\sigma+a) + j\omega}, \quad \sigma+a > 0$$

$$X(s) = \frac{1}{s+a}, \quad \Re\{s\} > -a$$



Effectively same as
← Fourier Transform

- Convergence dependent on both σ and a
 - Note: $\Re\{s\} = \sigma$
- Region of Convergence (ROC)
 - Finite integral (energy)

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Laplace Examples

Unit step function: $L\{u(t)\} = \int_0^{\infty} u(t) \exp(-st) dt$

$$= \int_0^{\infty} \exp(-st) dt$$

$$= \left[-\frac{\exp(-st)}{s} \right]_0^{\infty} = \frac{1}{s}, \quad \sigma > 0$$

Impulse function: $L\{\delta(t)\} = \int_{-\infty}^{\infty} \delta(t) \exp(-st) dt$

$$= \int_{0^-}^{0^+} \delta(t) \exp(-st) dt$$

Remember:

$$\int_{-\infty}^{\infty} f(t) \delta(t) dt = \int_{0^+}^{0^+} f(t) \delta(t) dt = f(0) \int_{0^+}^{0^+} \delta(t) dt = f(0) = \exp(-s0) \int_{0^-}^{0^+} \delta(t) dt = 1$$

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Interpretation of Laplace Transform

- Represents signals, $x(t)$, as sum of
 - growing/decaying cosine waves
- at all frequencies (continuous), $X(s)$
 - $\exp(\sigma t) |X(s)| d\omega / 2\pi$ is amplitude of growing/decaying cosine wave
 - In frequency band ω to $\omega + d\omega$
 - $\angle X(s)$ is phase shift of cosine wave
- parameter σ ($\Re\{s\}$) determines rate of growth or decay
 - Note: $\sigma = 0$ is the Fourier Transform ☺
 - Constant amplitude cosine waves

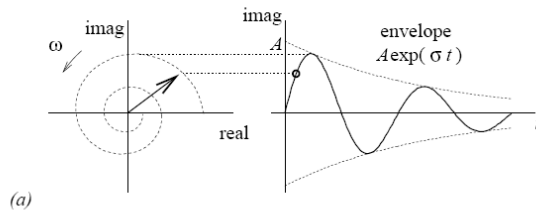
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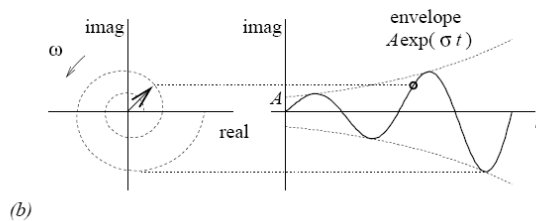
Complex Phasors

constant magnitude $\sigma = 0$
As per Fourier Transform

$$A \exp(st) = A \exp(\sigma t) \cos(\omega t) + j A \exp(\sigma t) \sin(\omega t)$$



Decaying $\sigma < 0$



Growing $\sigma > 0$

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Linear Transforms

- So far, we have looked at
 - Fourier series
 - Trigonometrical & Complex
 - Fourier transform
 - Laplace transform
- All represent signals as a
 - Weighted sum (or integration) of
 - Complex exponentials (that are orthogonal)
 - e.g., complex FS, $x(t) = \sum X_n \exp(jn\omega_0 t)$
- This relates directly to linear systems

Complex Fourier series:

$$x(t) = \sum_{n=-\infty}^{+\infty} X_n \exp(jn\omega_0 t)$$

Fourier transform:

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\omega) \exp(j\omega t) d\omega$$

Laplace transform:

$$x(t) = \frac{1}{2\pi j} \int_{\sigma-j\infty}^{\sigma+j\infty} X(s) \exp(st) ds$$

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Linear Transforms & Linear Systems

Useful, due to two properties of linear systems

1. Superposition principle
 - Inputs are complex exponentials (sinusoids)
 - Output is same exponentials, but with different weights, i.e., delay and amplify/attenuate input

$$H \{ax_1(t) + bx_2(t)\} = aH \{x_1(t)\} + bH \{x_2(t)\}$$

In other words, each phasor can be considered individually and output calculated by summation of the individual phasors

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Linear Transforms & Linear Systems

2. Ordinary differential equations (ODE)
 - Output $y(t)$ related to input $x(t)$ by ODE

$$a_0 y + a_1 \frac{dy}{dt} + \dots + a_n \frac{d^n y}{dt^n} = b_0 x + b_1 \frac{dx}{dt} + \dots + b_m \frac{d^m x}{dt^m}$$

$\frac{d}{dt} (\exp(jn\omega_0 t)) = jn\omega_0 \exp(jn\omega_0 t)$ Differentiation is simple:

- Frequency unchanged
- Magnitude changes

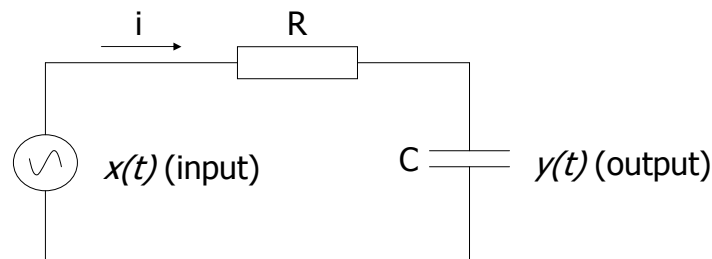
$$\frac{d^2}{dt^2} (\exp(jn\omega_0 t)) = (jn\omega_0)^2 \exp(jn\omega_0 t) \text{ (complex)}$$

Note: initially consider harmonically related sinusoids $n\omega_0$ as per Fourier Series

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Example RC Circuit



Using Kirchhoff's laws, system described (modelled) by ODE

(1 energy store \therefore 1st order)

$$a_0 y(t) + a_1 \frac{dy}{dt} = b_0 \exp(jn\omega_0 t) \leftarrow x(t) \text{ sinusoidal input}$$

$$y(t) + RC \frac{dy}{dt} = \exp(jn\omega_0 t)$$

Specifically:

$$a_0 = 1$$

$$a_1 = RC$$

$$b_0 = 1$$

derivation shortly...

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Example RC Circuit

$$\text{Note: } \frac{dy_n(t)}{dx} = (jn\omega_0) y_n(t)$$

- If input single sinusoid $x_n(t) = \exp(jn\omega_0 t)$
 - and system linear, (steady-state) output has form:

$$y_n(t) = K \exp(jn\omega_0 t) \leftarrow \text{Same frequency}$$

- Substituting (assumed) solution into ODE

where K is complex constant (weight)

Different amp. &/or phase

$$a_0 y_n(t) + a_1 (jn\omega_0) y_n(t) = b_0 \exp(jn\omega_0 t)$$

$$y_n(t) = \frac{b_0}{a_0 + (jn\omega_0) a_1} \exp(jn\omega_0 t)$$

$$y_n(t) = H_n \exp(jn\omega_0 t)$$

$$H_n = \frac{b_0}{a_0 + (jn\omega_0) a_1} = \frac{1}{1 + (jn\omega_0) RC}$$

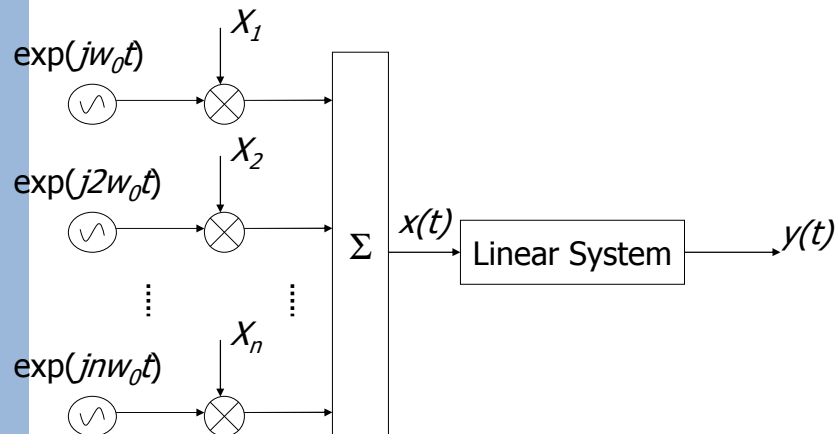
Where H_n is the system **transfer function** to this single phasor (K)

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Response of Linear System

- Input represented as Fourier series



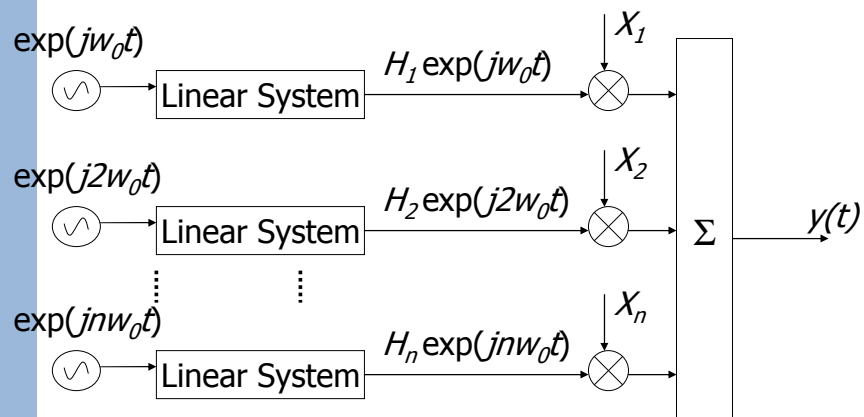
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Response of Linear System

Each phasor is orthogonal and \therefore can be evaluated separately

- Applying superposition principle
 - Applying individual phasors & shifting X_n terms

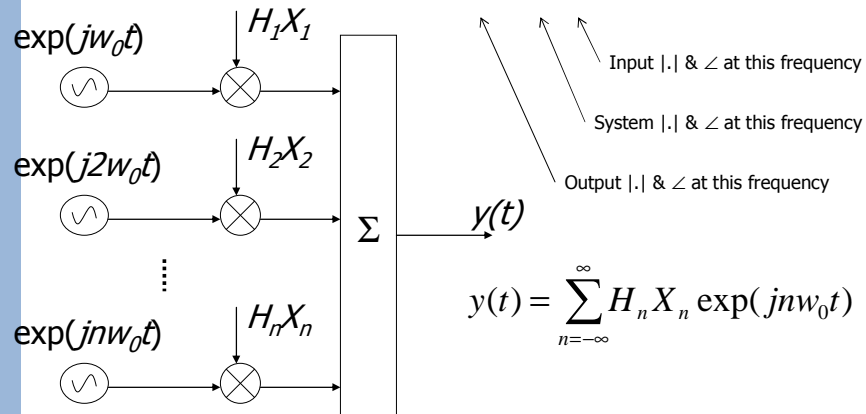


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Response of Linear System

- Output represented as Fourier series
 - output FS coefficients $Y_n = H_n X_n$



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General Approach

- Represent input as weighted sum of
 - Complex exponential **basis functions**,
 - e.g., FS: $\exp(jn\omega_0 t)$: sinusoids at harmonic frequencies
- Basis functions are orthogonal
 - Amplitude (& phase) at each freq. evaluated separately
- System described by ODE
 - Response to exponentials (differentials) easy to calculate
 - Frequency remains constant, Amp. & Phase change
 - e.g., if response 2nd harmonic is $2\omega_0 \exp(2j\omega_0 t)$
- System is linear
 - Output is sum of responses of individual exponentials
 - i.e., sum response at each frequency

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Laplace Transforms

- General approach was illustrated with
 - Periodic input (i.e., we used Fourier series)
 - Steady state response
- But, in general interested in
 - non-periodic input and
 - Both transient & steady state response
- So, we use the Laplace transform
 - Basis functions $\exp(st)$, where $s = \sigma + j\omega$
 - output response is $H(s) \exp(st)$
 - where $H(s)$ is system **transfer function**

Note: still orthogonal

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Laplace System Analysis

Steps in Laplace system Analysis,

1. Laplace transform input signal
 - $X(s) = L\{x(t)\}$
2. Calculate system transfer function
 - $H(s)$
3. Calculate (Laplace) output using multiplication
 - $Y(s) = H(s)X(s)$
4. Inverse Laplace transform
 - $y(t) = L^{-1}\{Y(s)\}$

Key: Calculating system transfer function: $H(s)$

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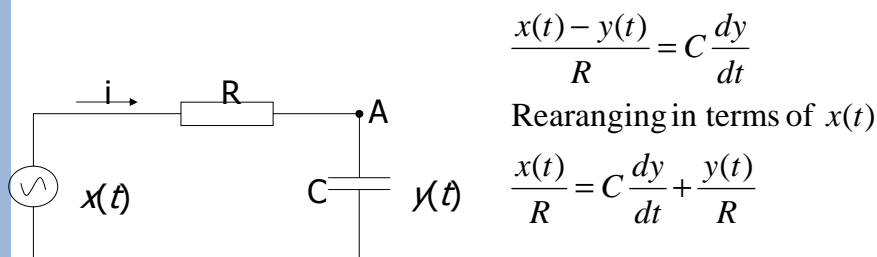


Laplace Transfer Function

- $H(s)$ completely defines the system
- Defined as:

$$H(s) = \frac{L\{y(t)\}}{L\{x(t)\}} = \frac{Y(s)}{X(s)}$$

Apply Kirchoff's current law at node A:



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Laplace Transfer Function

Note: $L\left\{\frac{d}{dt}f(t)\right\} = sF(s) - f(0^+)$

Taking Laplace Transforms

$$\frac{X(s)}{R} = C\{sY(s) - y(0)\} + \frac{Y(s)}{R}$$

Assume zero initial conditions $y(0) = 0$

$$\frac{X(s)}{R} = \left\{Cs + \frac{1}{R}\right\}Y(s)$$

Transfer function (first order LPF):

$$H(s) = \frac{Y(s)}{X(s)} = \frac{1}{(1 + RCs)}$$

Example 1.9
MGT

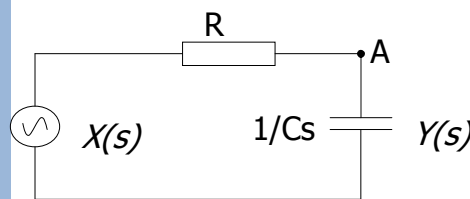
Note: similarity to H_n for FS

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Laplace Circuit Analysis

- Transform circuit elements
 - then apply Kirchoff's current law
 - Impedance of Capacitor = $1/Cs$
 - (Note: impedance of inductor = Ls)



$$\frac{X(s) - Y(s)}{R} = \frac{Y(s)}{1/Cs} = CsY(s)$$

$$H(s) = \frac{1}{(1 + RCs)}$$

This is quick and easy way of doing circuit analysis

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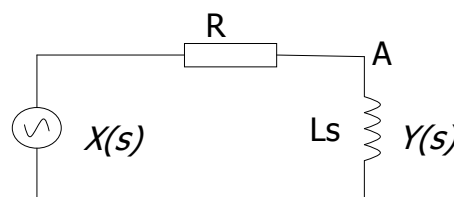


Laplace Circuit Analysis

- Impedance of Inductor = Ls

Note: $L \left\{ \int_0^t f(\xi) d\xi \right\} = \frac{F(s)}{s}$

By Kirchoff's current law: $\left(\frac{x(t) - y(t)}{R} = \frac{1}{L} \int y(t) dt \right)$



$$\frac{X(s) - Y(s)}{R} = \frac{1}{sL} Y(s)$$

$$H(s) = \frac{1}{\left(1 + \frac{R}{Ls}\right)} = \frac{Ls}{(Ls + R)}$$

First order HPF

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Summary

- Laplace transform similar to Fourier
 - Applicable to broad range of signals
 - Most one-sided (causal) finite energy and power
- Particularly useful for
 - solving ODE's i.e., analysing linear, time-invariant systems (e.g., circuit analysis)
- Based on summation (integration) of
 - (orthogonal) exponential (basis) functions
 - like Fourier series and transform
 - System response scaled versions of these
 - amplitude and phase change (only) at each frequency